A) Amendment to the Claims:

1-10. (Cancelled)

11. (Currently Amended) A precision auto alignment method for incident angle of an ellipsometer, wherein the precision auto alignment method emprising comprises the steps of:

measuring tilt and translating angle errors according to incident angles of a polarizing unit at a first predetermined position;

compensating each the errors by moving a light spot reflecting from the a specimen onto a center of the detector's entrance aperture;

calculating the tilt and translating angle errors from by repeatedly performing the said measuring and compensating steps above for the polarizing unit located at a subsequent predetermined position; and

correctly aligning incident angle for the ellipsometer by <u>compensating for</u> the <u>calculated</u> tilt and translating angle errors.

12. (Currently Amended) The precision auto alignment method according to claim 11, wherein the measuring step comprising comprises:

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measuring a first set of the tilt and translating errors as the light spot is centered on the detector's entrance aperture when the polarizing unit and analyzing <u>unit</u> are set at a first incident angle; and

measuring a second set of the tilt and translating errors as the light spot is centered on the detector's entrance aperture when the polarizing unit and analyzing <u>unit</u> are set at a second incident angle.

13. (Currently Amended) The precision auto alignment method according to claim 11, wherein the compensating step comprising comprises the steps of:

accessing the light spot to a <u>an</u> entrance aperture of <u>said</u> detecting unit of the <u>said</u> ellipsometer by tilting a specimen on <u>said</u> specimen stage of the <u>said</u> ellipsometer; and

centering the light spot to a <u>an</u> entrance aperture of <u>said</u> detecting unit by obtaining a half maximum intensity and at the same time a half position between two positions <u>have having</u> the same intensity.

14. (Currently Amended) The precision auto alignment method according to claim13, wherein the centering step comprising comprises the steps of:

obtaining a first center position in a X direction at a first half intensity of the first maximum intensity of between two x positions which have a first intensity; and

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a step of obtaining a second center position in a Y direction at a second half intensity of the second maximum intensity between two y positions which have a second intensity.

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